# GREMLINS A Tool Infrastructure for System Emulation



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# Designing a Tool Set for Exascale Co-Design





Architecture
Emulation
(GREMLIN)

Architectural
Simulation
(SST)

Holistic Performance Modeling in ExMatEx

- Analytical models provide high-level trends
  - But don't cover low level details
- Simulations enable access to architectural details
  - But are slow and difficult to use with complex codes / validation?
- Augment with emulation techniques
  - Run complex codes on real systems





#### The GREMLIN Idea



- Can we make a Petascale class machine behave like what we expect Exascale machines to look like?
  - Exascale machines will be
    - Resource limited (power, memory, network, I/O, ...)
    - Have less favorable compute/bandwidth ratios
    - Higher fault rates and lower MTBF rates
- GREMLINs are a set of techniques to emulate such behavior
  - Framework to couple range of "bad behaviors"
  - Transparent to system and (mostly) to applications
- The role in the Co-Design process
  - Evaluate proxy-apps with GREMLINs and compare to baseline
  - Determine bounds of behaviors proxy apps can tolerate
  - Drive changes in proxy apps to counter-act GREMLINs





#### **Broad Classes of GREMLINs**



#### Power

- Impact of changes in frequency/voltage
- Impact of limits in available power per machine/rack/node/core

#### Memory

- Restrictions in bandwidth
- Reduction of cache size
- · Limitations of memory size

## Resiliency

- Injection of faults to understand impact of faults
- Notification of "fake" faults to test recovery

#### Noise

- Injection of controlled or random noise events
- Crosscut summarizing the effects of previous GREMLINs





## **Implementation Principles**



#### Individual GREMLINs are implemented as modules

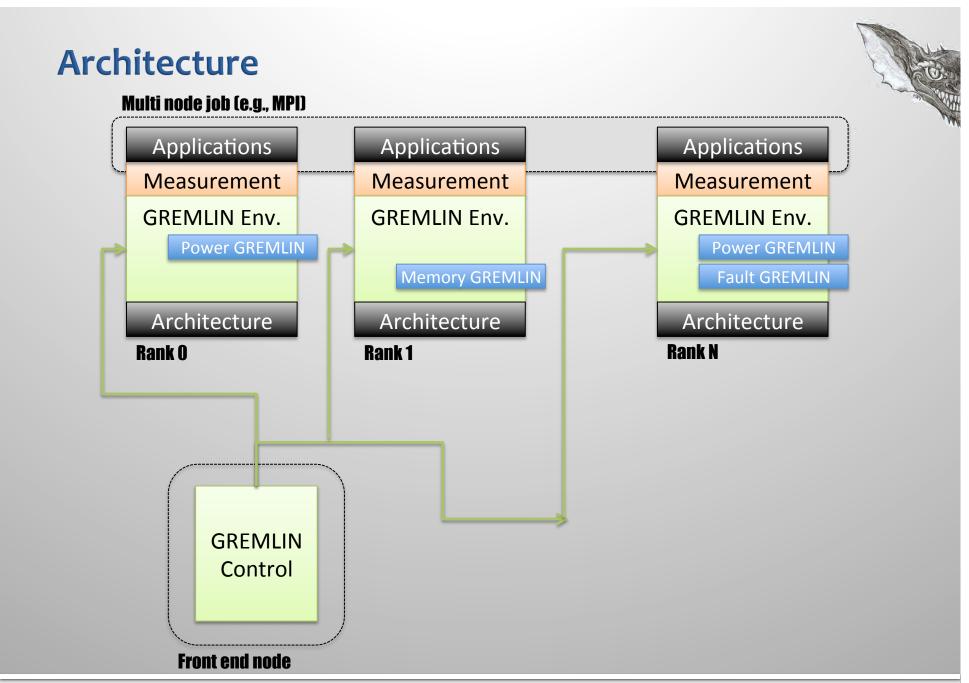
- One effect at a time
- Orthogonal to each other
- Each GREMLIN has "knobs" to control behavior

## Infrastructure to allow loading of GREMLINs

- Easy experiment setup using P<sup>n</sup>MPI (infrastructure to manage tools)
  - Enables stacking of PMPI tools
  - Transparent to applications
  - Concurrent use of multiple GREMLINs/effects
- Interactive access to GREMLIN "knobs"
  - Goal: Python (or similar) driver to influence behavior
  - Scalable infrastructure (CBTF) for data collection and analysis











# Needed: Redesign of P<sup>n</sup>MPI



#### Current design of P<sup>n</sup>MPI is limited

- Static tool stacks
- Focused on MPI only

## Enable more dynamic loading options

- Load/enable modules on the fly
- More flexible configurations
- Separate tool stacks for each process

## Interceptions of new APIs beyond MPI

- How to integrate OMPT?
- Wrapping library APIs

## Integration with MPlecho

Cloning of individual ranks to allow concurrent parameter studies





# **Designing and Deploying a GREMLIN**



## Step 1: Identify target resource

Which resource is supposed to be reduced/controlled/injected into?

## Step 2: Find mechanism to control/restrict resource

- Hardware mechanisms (e.g., RAPL)
- Direct software techniques (e.g., injection)
- Indirect software techniques (resource stealing)

#### Step 3: Measurement techniques

- Application performance metrics
- Co-execution with tools

#### Step 4: Mitigation mechanisms

- How can the effect of a GREMLLIN can be mitigated?
- Design of new runtime systems (e.g., Adagio)
- Fault resilience techniques to react to fault injections





#### **Power GREMLINS**



## Investigate impact of constrained power on applications

- Changes in frequency/voltage to save power
- Overall power caps imposed by machine limits (per system/rack/...)
- Local power caps for overprovisioned chips with dark silicon

#### Implementation

- Access to power measurements on Intel Sandy Bridge and BG/Q
- Changes of power caps on Intel Sandy Bridge using RAPL
  - Production machine with the ability to do large scale runs
  - Emulation of over provisioned systems
- GREMLIN functionality mainly limited to initialization





# **Example: CoMD under Multiple Power Bounds**

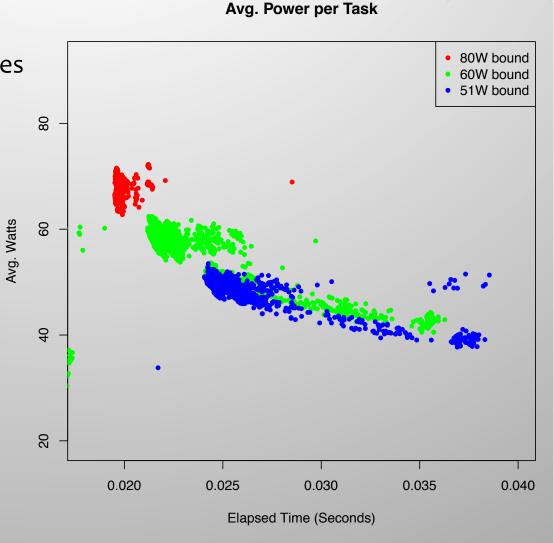


#### MD proxy app

- 128 MPI ranks over 8 nodes
- Dual socket 8-core
- RAPL measurements (avg. package power)

#### Observations

- Lower cap leads to lower performance
- Lower cap leads to more variation
- Power capping can lead to load imbalance





# **Power Analysis with GREMLINS**



#### Co-Design questions

- What is the optimal configuration for a given power budget?
- How will we deal with over-provisioned systems?
- Which parts of a code a most sensitive to power caps?
- How do automatic techniques interfere with the software stack?
- How to direct power where it is needed?

## Mitigation options

- Critical path based analysis and power control
- Global information to steer local adaptations

## Requirements

- Precise, predictive power models
- Flexible access to power control mechanisms in hardware





## **Memory GREMLINs**



## Investigation of limitations in the memory system

- Identification of non scalable memory requirements
- Investigation of "breaking points" for apps wrt. bandwidth/caching

## Implementation (targeting size)

- Wrappers of all memory allocation routines
- Allocate multiple times the size of the request (or tracking/extrapolating)

## Implementation (targeting bandwidth/caches)

Resource stealing (more on next slide)

## Mitigation mechanisms

- Locality optimizations (app)
- Communication avoiding algorithms (app)
- Scheduling optimizations (system)





# **Measurements Using Resource Stealing**



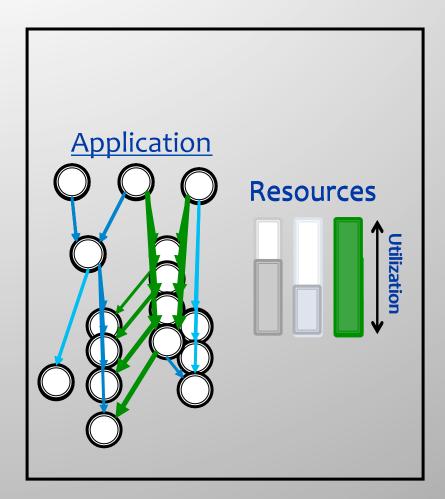
#### Overload resource

- Observe impact on application
- Study breaking point



# Implementation:Interference workload

- Additional threads adding bandwidth to a bus
- Separate thread utilizing a predefined part of the cache







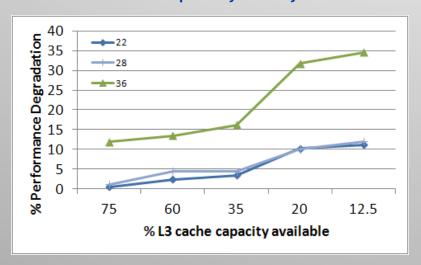
## **Parallel Application Study: Lulesh**



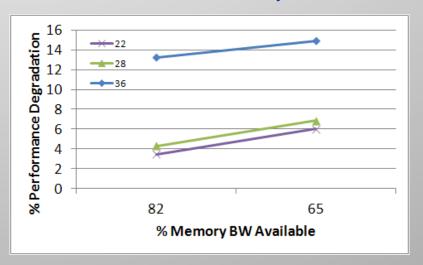
## Lulesh: Shock Hydrodynamics proxy app

- 64 MPI ranks, one task per socket / two per node
- Cache interference: random touches in predefined memory region
- Bandwidth interference: walk large buffer

#### Cache Capacity Analysis



#### Bandwidth Analysis







# **GREMLINs** (Resiliency)



#### Investigation of reduced reliability

- What can applications tolerate as is?
- What resiliency techniques are needed if faults go beyond that?
- At what point does a system become infeasible?

## Implementation (targeting actual faults)

- Fault injection with various mechanism
  - Binary rewriting (DynInst), LLVM, dynamic rewriting (PIN), ...
- Vulnerability studies
- Recovery testing

## Implementation (targeting "fake" faults)

- Injection by invoking correction handler inside the application
- Evaluate overhead and feasibility of mitigation mechanisms





## **Early Study on Application-Level Recovery**



#### Simple retry code blocks

- Programmer annotates (or protect) code block
- If error occurs, code block is re-executed
- Retry until block terminates without errors

#### Original code

```
void function(double *array)
{
    for (...)
        array[i] = ...
}
```

#### Annotated code

#### Fault model

- Hardware errors detected by hardware
- Notification through OS that triggers RETRY block
- Triggered by a GREMLIN ("fake" fault)





# **Try/Catch Methods in LULESH**

#### Method 1 MAIN\_FUNC\_ONLY

```
main() {
   TRY {
     while() {
        funct1();
        funct2();
        funct3();
     }
   }
}
```

# Method 2 CORE\_FUNCTIONS

```
main() {
   TRY {
     while() {
        TRY { funct1(); }
        TRY { funct2(); }
        TRY { funct3(); }
     }
}
```

```
Method 3 CORE_LOOP
```

```
main() {
    TRY {
        while() {
            TRY {
                funct1();
                 funct3();
                 }
        }
    }
}
```

#### **LULESH**

```
main() {
    /* init...*/
    while() {
        funct1();
        funct2();
        funct3();
    }
}
```

```
Method 4 i_ITERATIONS_BACK
```

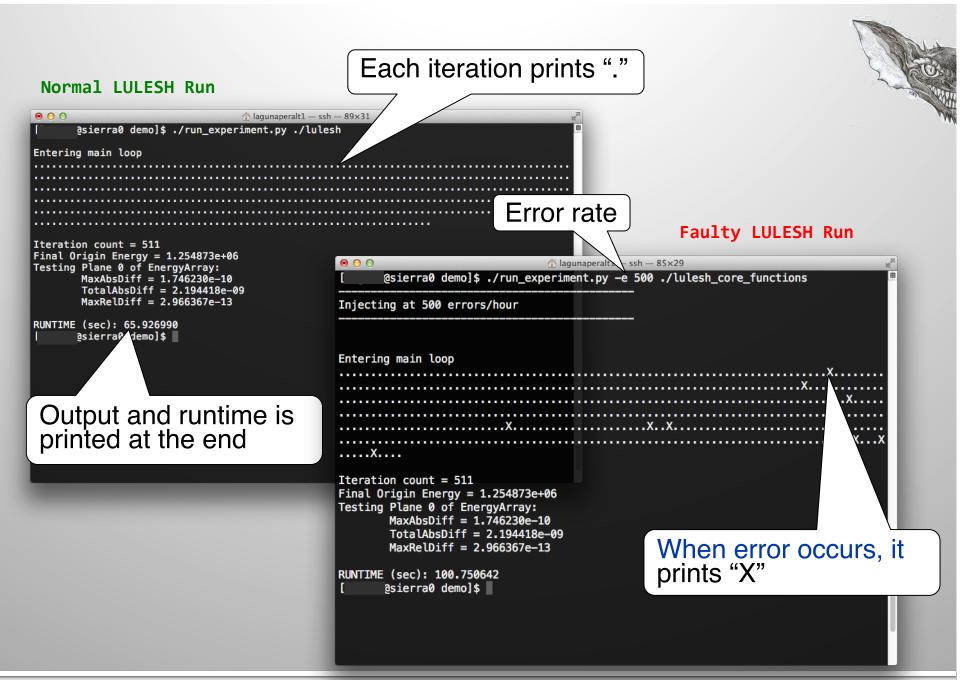
```
main() {
   TRY {
     while() {
        TRY(25) {
          funct1();
          funct2();
          funct3();
        }
    }
}
```

```
main() {
   TRY {
      while() {
         TRY(100) {
         funct1();
         funct2();
         funct3();
      }
    }
}
```

```
main() {
    TRY {
        while() {
            TRY(200) {
                funct1();
                funct2();
                funct3();
                }
        }
    }
}
```

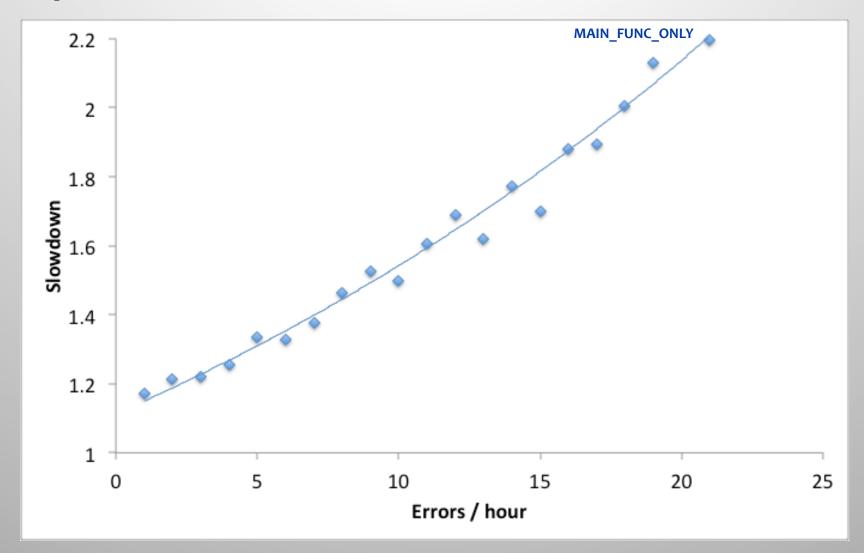
```
main() {
   TRY {
     while() {
        TRY(500) {
        funct1();
        funct2();
        funct3();
      }
   }
}
```



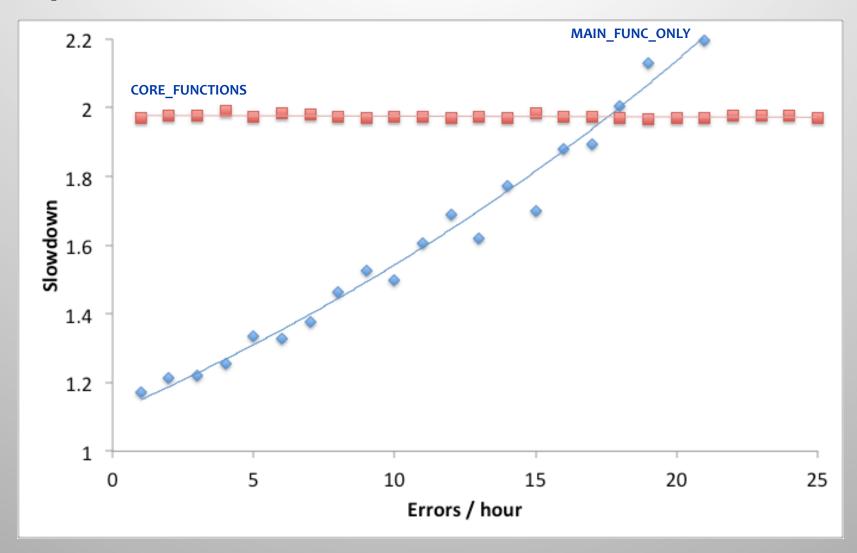




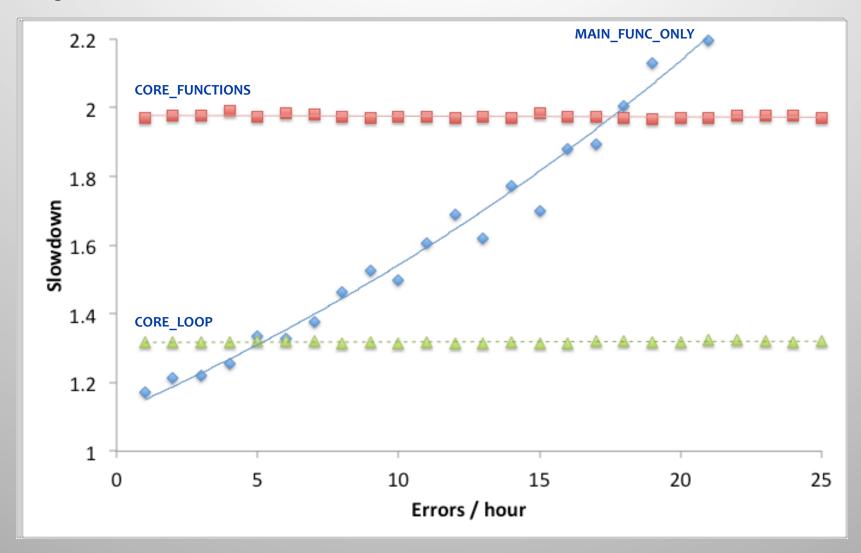




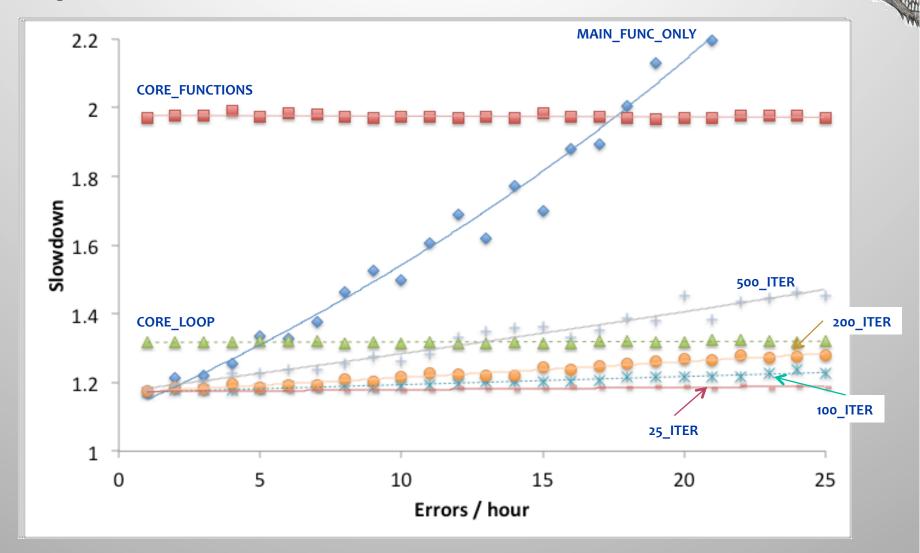














## **Co-Design Questions for Resilience**



#### Fault model, injection, and detection

- Integration of injections techniques into GREMLINs
- Study of error models
- HW/OS/RT APIs for reporting detected errors

## Mitigation mechanisms

- APIs for applications to expose vulnerable state
- Fault resilient algorithms
- Techniques inside the application to recover from faults
  - Code redundancy
  - Data reconstruction
- Investigate fault tolerant MPI proposals
- Options for direct support in runtime systems





#### **Conclusions and Future Plans**



## Using emulation to support the co-design process

- Ability to execute full codes on real machines at scale
- GREMLIN approach imposes constraints to emulate future architectures

#### GREMLINs can cover many aspects of future systems

- Power constraints and their impact
- Constraint in memory resources
- Impact of faults and recovery techniques

#### Future work

- New GREMLIN/emulation techniques in hardware and software
- Ensemble of GREMLINs to enable large parameter studies more quickly
- Integration of GREMLINs into new programming models
- Integration with new scale bridging MPMD environments
- Planned for 9/13: release of the GREMLINs



